## AXPERT VT240S

### The World's Most Advanced Universal AC Drive

### **Features**

### 6 control modes

- · V/f variable torque control
- · V/f constant torque control
- Sensor-less vector control
- Closed-loop vector control
- · Sensorl-ess PM motor control
- Closed-loop PM motor control

### Intelligent

- · User-programmable built-in PLC
- · Application-specific features
  - PID control
  - Multi-pump control
  - Traverse control for fibre machines
  - Auxiliary motor control up to 5 motors
  - Spinning ring frame
  - Energy optimiser
  - Elevator program

### Environment-friendly

- . RoHS Directive compliant
- · Selectable Soft-sound switching frequency
- · High-efficiency operation
- · Dioxin-free plastic cases

### Global Design

- UL, cUL and CE compliant
- Fieldbus interfaces (Modbus, Profibus-DP, DeviceNet, CANopen, CC Link)
- · LED display as standard
- Multi-language LCD monitor as option
- Safe Torque OFF (STO) function
- · Engineered System with various options





AN ISO 9001: 2015 COMPANY

### **Model Number**

### AXPERT - VT240S - 2 P 2 H B F 2 000 Input voltage and capacity STO identification symbol. L: 200V Series None: STO not provided S : STO provided H: 400V Series Control PCB option. Main circuit option 1 000 indicates no option A: Standard 1 (no options) Operation panel selection. B: Standard 1 with dynamic braking resistor 0: None D: DC input 0. None 1: LCD type (V24-OP1) 2: LED type (V24-OP2) (Standard) 3: Chinese LCD type (V24-OP3) 4: High-resolution LCD type (V24-OP1A) E: Standard 2 Enhanced (no options) (TP5H~37H) V: Standard 2 with dynamic braking resistor Main circuit option 2 0: Standard F: Bilt-in EMC filter (Up to 5P5L/30H) R: Bilt-in DC Reactor (022L/037H and above)

### **Standard Specifications**

### 200V Series

	Item		Specifications												
	System		200V Series												
Тур	e (AXPERT-VT240S 🗆 🗆 🗆 )	0P7L	1P5L	2P2L	4P0L	5P5L	7P5L	011L	015L	018L	022L	030L	037L	045L	
	Rated Capacity [HP] �1	1	2	3	5	7.5	10	15	20	25	30	40	50	60	
Duty	Max. Continuous rated current [A]❖2	5	8	11	16	24	33	46	61	76	88	118	146	174	
<u></u>	Max. Applicable motor [kW]❖3	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	
Rating Normal	Carrier Frequency❖4		Standard 4 kHz (soft sound) : Variable between 1 and 15kHz												
# [_	Overload current rating		120% for 1 minute 140% for 2.5 seconds												
bme	Rated Capacity [HP] �1	0.5	1	2	3	5	7.5	10	15	20	25	30	40	50	
Equipment Rating  Duty Norm:	Max. Continuous rated current [A]❖2	3	5	8	11	16	24	33	46	61	76	88	118	146	
Heavy [	Max. Applicable motor [kW]❖3	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	
꽃	Carrier Frequency 4		Standard 4kHz (soft sound) ; Variable between 1 and 15kHz												
	Overload current rating		150% for 1 minute 175% for 2.5 seconds												
Power Supply	Rated input voltage/frequency			200 to 240V ± 10% 50 or 60 Hz ± 5% 200 to 230V ± 10% 50 or 60 Hz ± 5%											
Output	Rated output voltage ❖ 5		200 to 240 V (Max.)								200 to 230 V (Max.)				
Julpul	Output frequency range		0.1 to 440 Hz												
	EMC filter		Built-in (Standard) Externa								al (option)				
Main	DC reactor		External (option)									Built-in (option)			
circuit option	DBR control circuit		Built-in (Standard)								External (option)				
option	DBR resistor		Built-in (option)								External (option)				
tion	Installation system		V	Vall-moun	ted, Free-s	tanding type	(optional)	for 022L a	nd above						
Construction	Protective enclosure		IP20								IP00 (standard)				
So	Cooling method	Self-c	Self-cooled Forced air cooling							ling					
	Operating Environment					re :- 10 to 5 ation: 4.9m/s									

### ■ 400V Series

		Item	Specifications													
		System	400V Series													
	Type (AXPERT-VT240S □□□□)			1P5H	2P2H	4P0H	5P5H	7P5H	011H	015H	018H	022H	030H	037H	045H	055H
		Rated Capacity [HP] -1	1	2	3	5	7.5	10	15	20	25	30	40	50	60	100
	Duty	Max. Continuous rated current [A]❖2	2.5	3.6	5.5	8.6	13	17	23	31	37	44	60	73	87	108
_ n	nal [	Max. Applicable motor [kW]❖3	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55
Equipment Rating	Normal	Carrier Frequency❖4					Stand	ard 4 kHz	(soft sound	) : Variable	between 1	and 15kH	Ηz			
int R		Overload current rating		120% for 1 minute 140% for 2.5 seconds												
bme		Rated Capacity [HP] �1	0.5	1	2	3	5	7.5	10	15	20	25	30	40	50	60
.inb⊡	Duty	Max. Continuous rated current [A]❖2	1.5	2.5	3.6	5.5	8.6	13	17	23	31	37	44	60	73	87
	Heavy I	Max. Applicable motor [kW]❖3	0.4	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45
	He	Carrier Frequency❖4	Standard 4kHz (soft sound) ; Variable between 1 and 15kHz													
		Overload current rating	150% for 1 minute 175% for 2.5 seconds													
Pov Sup		Rated input voltage/frequency	380 to 480V ± 10% 50 or 60 Hz ± 5%													
Out	nut	Rated output voltage �5	380 to 480 V (Max.)													
Out	put	Output frequency range							C	0.1 to 440Hz						
		EMC filter	Built-in (option)													
Ma		DC Reactor		External (option)												
opti		DBR control circuit					Built-in	(Standard	)				E	External (option)		
		DBR resistor				Built-in (o	ption)					Ex	ternal (op	otion)		
i,	1011	Installation system				Wall-r	nounted Sta	ndard, Fre	e-standing	(option) 03	7H (37kW)	and abov	e.			
acito: ratouo	onis	Protective enclosure	IP20 IP00									IP00	STD			
	3	Cooling method	Self-c	ooled					For	ced air coo	ling					
		Operating Environment					re :- 10 to 50 tion: 4.9m/s									tton lint.

### 200V / 400V Series

	Item			Specifications											
	System			200V Series			400V Series								
	Type (AXPERT-VT240S □□□□)			075L	090L	075H	090H	110H	132H	160H	200H	250H	315H	400H	475H
		Rated Capacity [HP] �1	75	100	120	100	120	150	175	215	270	335	425	535	635
	Duty	Max. Continuous rated current [A]❖2	211	286	328	147	179	214	249	321	428	519	590	740	870
5	Jal	Max. Applicable motor [kW]❖3	55	75	90	75	90	110	132	160	200	250	315	400	475
Equipment Rating	Normal	Carrier Frequency❖4	Standard 4 kHz (soft sound) : Variable between 1 and 8kHz												
1 2 2	_	Overload current rating	120% for 1 minute 140% for 2.5 seconds												
l au		Rated Capacity [HP] •1	60	75	100	75	100	120	150	175	215	270	335	425	535
<u>i</u>	Duty	Max. Continuous rated current [A]❖2	174	211	286	108	147	179	214	249	321	428	519	590	740
-	Heavy [	Max. Applicable motor [kW]❖3	45	55	75	55	75	90	110	132	160	200	250	315	400
	무 무	Carrier Frequency❖4				Standard 4kHz (soft sound) ; Variable between 1 and 8kHz									
		Overload current rating	150% for 1 minute 175% for 2.5 seconds												
	wer pply	Rated input voltage/frequency	200 to 230V ± 10% 50 or 60 Hz ± 5%												
Ou	tput	Rated output voltage ❖5	200 to 230 V (Max.) 380 to 480 V (Max.)												
	.,	Output frequency range		0.1 to 440Hz											
M	ain	EMC filter	External (option)												
	cuit	DBR control circuit	External (option)												
ор	tion	DBR resistor						E	xternal (op	tion)					
	tion	Installation system					Wall-r	nounted (s	tandard) / F	ree-standi	ng (option)	)			
	Construction	Protective enclosure							IP00 (st	andard), IF	P20 (option	)			
	5	Cooling method							For	ced air coo	ling				
		Operating Environment					re :- 10 to 5 tion: 4.9m/s								n) or cotton lint.

- Note: 1. The output voltage indicates the output capacity [HP] at 200V for the 200V series, and 400V for the 400V series.
  - ❖ 2. Indicates the total effective value including the higher harmonics.
  - ❖ 3. Indicates the case for the standard 4-pole squirrel cage motor.
  - ❖ 4. If the carrier frequency exceeds 4kHz, the rated current must be reduced. Please ref. fig.1.
  - ❖ 5. An output voltage exceeding the input voltage cannot be attained.
  - ❖ 6. Any optional accessory will be provided at extra cost and to be specified in order clearly.

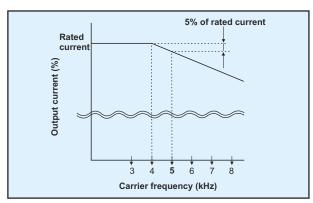


Fig. 1 Derating according to carrier frequency

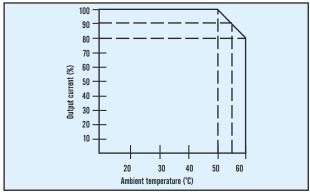


Fig. 2 Derating according to ambient temperature

### LCD panel (V24-OP1) - Optional

# Data display section (LCD) Output Frequency 00-0= 440.00 Hz Increase / decrease knob White indications LED Operation keys

### LED panel (V24-OP2) - Standard



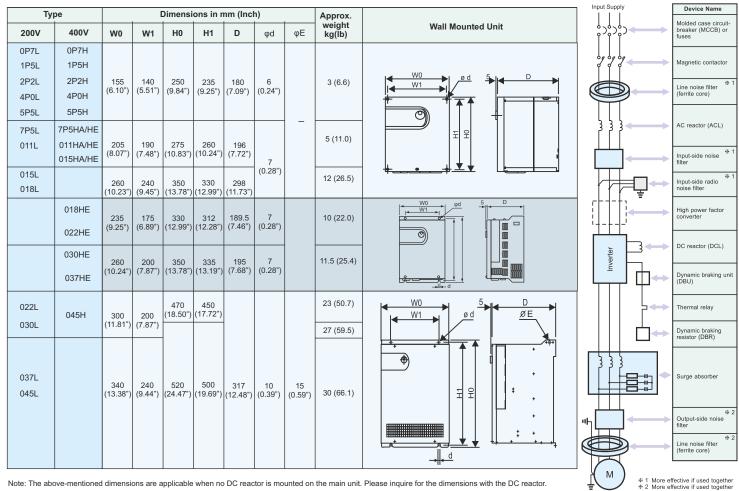
		V/f control	Sensor-less	Vector control with	PM motor control						
		VAIGORIGI	vector control	encoder	with encoder						
	Control Method		All digital control Sine wave approximation PWM								
Frequency Control	Transfer frequency	Mono-sound mode : 1 to 15 kHz (0.1 kHz increments)  Soft sound mode : Average frequency 2.1 to 5kHz  Frequency modulation method (3 tone modulation, 4 tone modulation)									
ency	Output frequency resolution		0.0	1 Hz							
Frequ	Frequency setting resolution		0.01 Hz (digital) 0.03% (analog) In respect to maximum frequency								
	Frequency accuracy	± 0.01% (digital) at 25 ± 10°C ± 0.0% (analog) at 25 ± 10°C									
	Voltage/frequency Characteristics	Middle V/f point of five points randomly set between 3 and 440Hz can be set	between 9999	mly set 150 and 9min <sup>-1</sup> 180Hz)	Randomly set between 150 and 9999min <sup>-1</sup> (max. 210 Hz)						
	Torque boost	Manual / Automatic Selective		_							
	Max. torque boost	Max. torque for applicable motor is output when used with automatic tuning	_								
	Automatic tuning	Automatic meas Basic method w	asurement of motor constants urement of various parameters hich does not rotate motor, and which rotates motor are availab	Encode phase adjustment Magnetic pole position estimation							
	Starting frequency	Set between 0.1 and 60.0 Hz	_								
Control specifications	Starting torque	- At 200% or more using Amtech standard motor. (*3) - Attainment time approx. 3 sec.	_								
Spec	Acceleration / deceleration time		0.01 to 6 ation/deceleration time x 2, jog	0,000 sec	shion x 8						
Contro	Acceleration / deceleration mode			racter selective							
Ü	Operation method		3 mode selective - Forward run/revese run - Run stop/forward run reverse run - Forward run pulse/revese run pulse/stop								
	Stop method	Deceleration stop in respect to run, emergency stop and inching, coast to stop selective									
	DC Braking	Braking start frequency, randomly set between 0.1 and 60.0Hz Braking voltage, Randomly set between 0.1 & 20.0%  Braking start speed set between 0.00 and 50.00% Braking current set between 50 and 150%  Braking current set between 50 and 150%									
	Braking Time		Set between 0.0 and 20	0.0 seconds							
	Output frequency	0.1 to 440 Hz	0 to 1	80 Hz	0 to 210 Hz						
	Control range	Simple ASR function is not specified	1 : 100	1 : 1000	1 : 100						
	Constant output range	Up to 1 : 7	Up to 1 : 2	Up to 1 : 4	Up to 1 : 1.5						
	Control accuracy (At Fmax ≥ 50Hz)	± 0.01%	± 0.5% ± 0.01%		± 0.01%						
	Control response	Simple ASR function is not specified	5Hz	30Hz	_						
Setting	Multi-step frequency Setting	frequency  8 steps  Acceleration / Deceleration time as programmable  5-bit non-encode mode									

			V/f control	Sensor-less vector control	Vector control with encoder	PM motor control with encoder					
					<b>*</b> 1	<b>*</b> 2					
	Ratio	o interlock setting	During remote setting mode y=Ax+B+C y: Operation results x: Operation input A: 0.000 to ± 10.000 B: 0.00 to ± 440Hz C: Auxiliary input with output upper / lower limit	During remote setting mode y=Ax+B+C  results input 10.000 A: 0.000 to ± 10.000  440Hz B: 0 to ± 7200 min <sup>-1</sup> (120Hz)  reput C: Auxiliary input							
gu B	Skip	Frequency	Three places can be set Width can be varied between 0.0 and 10Hz								
Setting	Slip	compensation	Operation/non selective Slip compensation gain : 0.0 to 20.0	o compensation gain :							
	Auto	matic run function		10-step automat Synchronous / Asyn							
	Built-	in PLC function	Arithmetic operations, logical operations, size comparison and LPF operations, etc., in respect to the sequence input/output and analog input/output are possible.  Program capacity: max.64 commands *5 banks, operations cycle: 1 bank in 2ms								
	Othe	rs	PID Control Pick-up Automatic Start Restart after instantaneous power failure Reverse run prevention  Traverse pattern Deceleration control at power failure Multi-pump Spinning frame								
utbut	Oper	ration panel	Local/remote changeover operation, forward run/reverse run direct operation, reference, change and copy of all parameters  Mountable outside unit (extension cable max. 3m)								
Control input/output		LCD type Optional	Display : 16 characters *2 lines Status display LED : 4 points Operation : Operate with knob and set key								
ontrol		LED type Standard	Display : 7-segment LED x 5 digits + sign Status/unit display LED : 7 points  Operation : Operate with ▲▼ keys + set key								
	Sequ	uence input	_	k/source changeable, PSI7 is u		"					
ontrol input/output	Sequ	uence output	(programmable), PS03 is use The programmable details ca	ed as pulse train output an be changed between speed	: 1 point (programmable), oper detection, pre-charging completeached, acceleration, decelerat	ete, reverse run,					
Control ir	Freq	uency setting	Voltage input (0 to 10V, 0 to Voltage input (0 to ±10V, 0 to Pulse train input (max. 10kH.	±5C, 1 to 5V): 1 point (used w	to 20mA, 0 to 20mA) : 2 points vith sequential ratio operation o	r PID feedback etc)					
Control	Mete	er output		current output (4 to 20mA): 2 p uency, output voltage, output c							
Communication Control	Seria	al Interface	Connection method: RS485, Transmission method Start-s	2-wire type, Transmission distatop synchronization, half-duple	ledicated communication (standance: total extension distance are communication, Baud rate: sunits, Error detection: Sum che	l50m or less, elect from					
	Prev	entive			three stages), overcurrent limit, overload (cooling fin overheat)						
	Shut-off		overload warning, carrier frequency automatic reduction at overload (cooling fin overheat) (selective)  Overcurrent, over voltage, under voltage, IGBT fault, phase failure (input/output), overload, cooling fin temperature rise, ground fault, other self-diagnosis								
ion	Fault	t history	Past four faults recorded. Recorded details: primary cause, secondary cause, output frequency/current/DC voltage before shutoff, hardware latch, cumulative ON time, cumulative operation time								
Protection	Over withs	rload stand level	Normal-duty setting 120% for 1 minute, 140% for 2.5 seconds (reduced to 60% for 1 munute from 1Hz to 0.1Hz) Inverse time characteristics Heavy-duty setting 150% for 1 minute, 175% for 2.5 seconds (reduced to 75% for 1 minute from 1Hz to 0.1Hz). inverse time characteristics								
	Auto	-Restart	Programmable between 0 ar	nd 10 times							

Note : ❖ 1. Encoder option PCB is required.

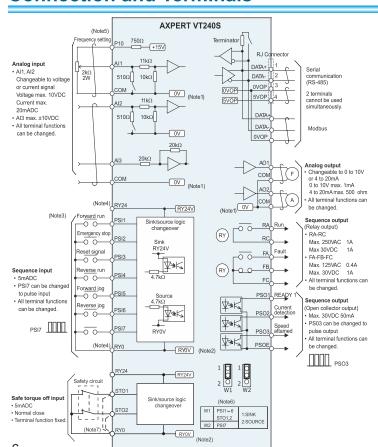
- $\ \ \, \ \ \, \ \ \, \ \ \,$  2. This is for the standard PM motor. The PM speed detection PCB is required.
- $\clubsuit$ 3. Differs according to the motor capacity, rated voltage and rated frequency. If 45kW is exceeded, starting torque is > 150%.

### **System**



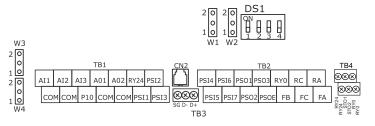
### **Connection and Terminals**

6



### Control terminal

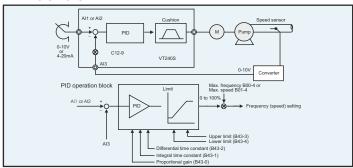
- The terminal block is laid out in two rows.
- Terminal screw size is M3



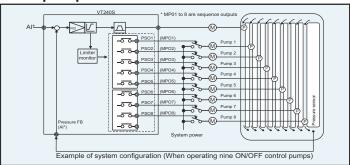
### (Notes)

- $1. \ \ Four COM \, terminals \, are \, internally \, connected.$
- 2. No connection shall be made between RY0, COM and 0VOP since this section is isolated.
- $3. \ \ \, \text{This diagram is an example of the sink logic connection}.$
- 4. RY24 and RY0 must not be shorted.
- 5. P10 and COM must not be shorted.
- $6. \ \ Short-circuit\ plugs\ W1\ and\ W2\ are\ set\ to\ the\ 1\ side\ (sink)\ as\ the\ default.$
- STO1 and STO2 are shorted with a short-circuit wire as the default. Remove this wire when connecting a safety circuit.

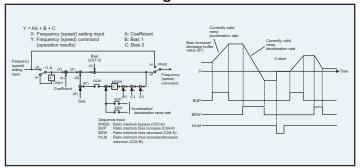
### **PID Control**



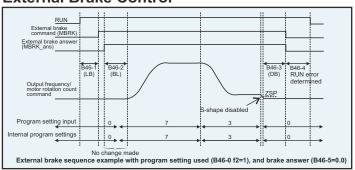
### **Multi-pump Control**



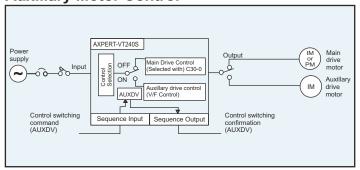
### **Ratio Interlock Setting**



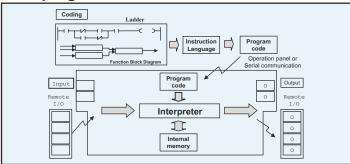
### **External Brake Control**



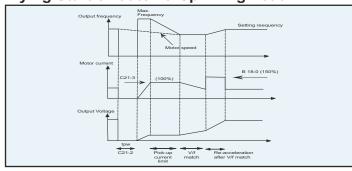
### **Auxiliary Motor Control**



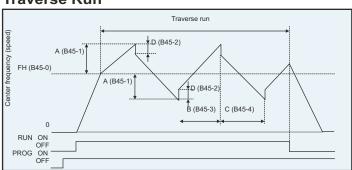
### User-programmable built-in PLC



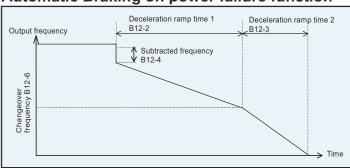
### Flying Start or Catch-a-Spinning Load



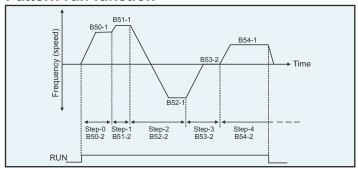
### **Traverse Run**



### **Automatic Braking on power failure function**



### Pattern run function



### **OUR OTHER OFFERINGS**

### **MOTOR CONTROL**



### "DRIVE FOR SUCCESS"

We provide complete motor control system solutions or individual system components to address industry specific requirements and optimize your process.

Our solutions are simple, compatible and environment friendly, resulting in efficient production, cost optimization and minimizing human intervention. It even leads to energy conservation especially in typical Fan, Blower applications.

### **Flagship Solutions**

- Axpert-Eazy+ Series VFD
- Axpert-VT240S Series VFD
- Axpert-Hivert Series Medium Voltage Drive
- Axpert-Opti torque Soft Starter
- Axpert-Eazy HF-High Frequency Drive

### **Applications**

- Fans, Blowers, Pumps
- Compressors, Centrifuges
- Agitators & Conveyors
- Oil & Gas
- Mining

### **AUTOMATION**



### "AUTOMATION. MADE EASY"

"Automation Made Easy" is our philosophy to simplify the increasing complexity of modern production systems through our Amtech-Jetter PROCESS PLC technology platform.

Our 30 years experience in Machine, Line, Plant and Networking Automation has helped us to find the best solution in terms of functionality, sustainability and efficiency.

### **Flagship Solutions**

Jet Control series PLC Controllers, Expansion Modules, Jet view Soft SCADA, HMIs, Jet Move series Servo and Axes Control System.

### **Applications**

- Paper Machine Automation
- Textiles Manufacturing
- Packaging
- Winder Machine
- Crane & Material Handling Equipment
- CNC Machines
- Semiconductor Assembly Line
- Retrofit solutions

### **POWER QUALITY**



### "ONE STOP SOLUTION TO QUALITY POWER"

Amtech's Power Quality Solutions offer you the synergy of multiple benefits - energy conservation, enhanced operational efficiency and reliability through a dedicated range of products and services.

### **Products**

- Active Front end Converter
- Active Harmonic Filter (AHF)
- Active Static VAR Compensator (STATCON)
- Static Harmonic Converter
- Harmonic Reactor
- Sinus Filter
- EMI/RFI Filter

### **Services**

- Harmonic Audit and Solutions to comply with IEEE-519 standard
- System design, optimization & pay-back analysis
- Consultancy for Power Quality improvement
- Training on Power Quality Management
- Energy Audit and solutions by experienced BEE certified professionals

### **INDUSTRIAL ELECTRONICS**



### "YOUR TECHNOLOGY

Amtech's Power Electronics Engineering Services offer technology solutions to independent R&D labs, industrial segments like Traction, Oil & Gas, Automotive and Renewable Energy for wind and solar to reduce your time to market.

### **Products**

- Traction Drive
- High Voltage Power Supply
- Battery back-up drive & systems for critical loads
- Wind Power Converter
- Grid tied Solar Inverter
- Digital Heater controller
- Batter charger
- Drive Train

### **Services**

- Power Electronics Engineering Services
- Customized solutions for industry specific applications
- Solutions for Oil, Gas & Mining
- Power Electronics product development & testing
- Product verification & validation
- Retrofit Solutions



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